**DATASHEET** 

# Magellan® MC58113 Series Motion Control | Cs PERFORMANCE MOTION DEVICES MC58113

# Magellan® MC58113 Series Motion Control ICs

provide high performance motion control with an integrated digital current loop. Available as a single, one-axis IC, the MC58113 IC is a programmable device that provides positioning, velocity, and torque control for Brushless DC, DC Brush, and step motors.

# A Powerful Motion Controller

Magellan Motion ICs are complete motion controllers requiring only an external bridge circuit or amplifier to be functional. They are driven by a host using either a parallel bus, SPI (Serial Peripheral Interface), CANbus 2.0B, or RS232/485 serial. User selectable profiling modes include S-curve, trapezoidal, velocity contouring and electronic gearing. PID servo loop compensation utilizes a 32-bit position error and includes velocity and acceleration feedforward. High performance FOC (field oriented control) provides high accuracy, ultra-low noise motor operation.

# **Easy to Use and Program**

All Magellan Motion Control ICs provide a flexible and powerful instruction set to initialize and control motion axes, monitor performance, and synchronize overall machine behavior. Working with Magellan ICs, and Pro-Motion® development software makes it fast and easy to graph and analyze system performance; while C-Motion® language allows you to develop your own application using C/C++.

## Flexible Offering

There are four MC58113 Series ICs, each packaged in a single 100-pin TQFP operating at 3.3 V. The MC51113 provides dedicated control of DC Brush motors, the MC53113 provides control of three-phase Brushless DC motors, the MC54113 provides control of two-phase step motors, and the MC58113 can be software selected to provide control of any of these motor types.

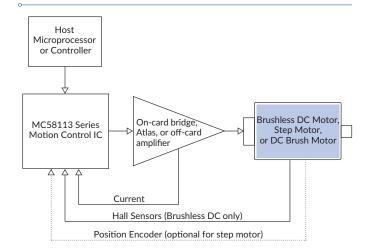


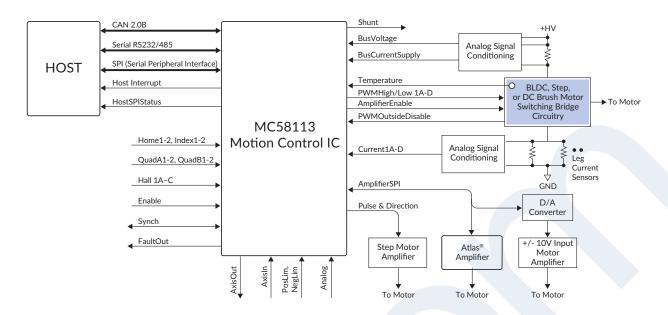
# **FEATURES**

- Single axis, single IC
- Position, velocity, and torque control
- Brushless DC, DC Brush, and step motor control
- S-curve, trapezoidal, velocity contouring, and electronic gearing profiles
- SPI (Serial Peripheral Interface), serial RS232/485, and CANbus communications
- 1.5 axes (primary and auxiliary encoder) control
- Advanced PID filter with velocity and acceleration feedforward
- High performance current control of each motor phase
- High/Low switching amplifier control with programmable deadtime and charge pump refresh
- Velocity, position and acceleration changes on-the-fly
- Programmable position loop time from 50 μsec to 1.1 sec

- FOC (field oriented control)
- Incremental encoder quadrature input (up to 25 Mcounts/sec)
- Synch pin feature allows multiple axes to be synchronized to <1 μsec
- Internal motion trace NVRAM for performance optimization
- Overcurrent, over/ undervoltage and overtemperature detect
- Directional limit switch, index, and home inputs
- Axis settled indicator, tracking window and automatic motion error detection
- General-purpose analog input
- Programmable dual biquad filters
- Programmable acceleration and deceleration values
- Compact 100-pin TQFP package

# CONFIGURATION





# MC58113 SERIES SPECIFICATIONS

Demonstrate	Value			
Parameters	Value			
Configurations	MC51113 - DC Brush motor MC53113 - Brushless DC motor MC54113 - Step motor MC58113 - Motor type software selectable			
Host communication options	Serial RS232/485 CANbus 2.0B SPI (Serial Peripheral Interface)			
Position range	-2,147,483,648 to +2,147,483,647 counts			
Velocity range	-32,767 to 32,767 counts/sample			
Acceleration and deceleration range	0 to 32,767 counts/sample <sup>2</sup>			
Jerk range	0 to 1/2 counts/sample <sup>3</sup>			
Servo loop range	50 μsec to 1.1 sec			
Position error resolution	32 bits			
Commutation rate	20 kHz			
Microsteps per full step	Programmable, up to 256			
Signal inputs axis 1	QuadA/B, Index, Home, Hall A/B/C AxisIn, Pos/NegLimit			
Signal inputs axis 2	QuadA/B, Index, Home			
Maximum encoder rate	25 Mcounts/sec			
Internal trace buffer	32 KB			
Internal NVRAM buffer	2 KB			
Operating temperature (Ta )	-40° C to 85° C			
Supply voltage operating range (Vcc)	3.0 V to 3.6 V			
Package and dimensions	100-pin TQFP, 14 x 14mm			
	<del></del>			

# **AMPLIFIER CONNECTION OPTIONS**

On-board PWM amplifier circuitry					
PWM output rate	20, 40, or 80 kHz				
Current control modes	FOC (field oriented control), A/B, third leg floating, voltage modefloating, voltage mode				
Current loop rate	20 kHz				
PWM output modes	High/Low, Sign/Magnitude, 50/50				

# External +/- 10V input amplifier Amplifier SPI bus serial 16 bits DAC

Pulse & direction input amplifier			
Pulse and direction output rate	up to 1.0 Mpulses/sec		

# ATLAS® Digital Amplifiers

ATLAS® Digital amplifiers are compact single-axis amplifiers that provide high performance torque control of DC brush, brushless DC, and step motors. They are packaged in a Compact or Ultra Compact solderable module and utilize standard through-hole pins for all connections.

Voltage Input	12-56 VDC			
Microstepping resolution	256			
PWM frequency	20, 40, 80 kHz	The state of the s		
<b>Current Loop rate</b>	20 kHz	THE PARTY OF THE P		
Power rating options	75W, 250W, 500W			
Mechanical Dimensions	Ultra Compact size: 1.05" x 1.05" x 1.53" (27mm x 27mm x 13mm)			
	Compact size: 1.52" x 1.52" x 1.60" (39mm x 39mm x 15mm)			

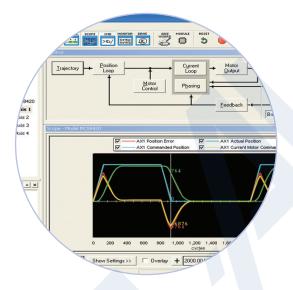
# **Development** Tools



# **INCLUDES**

- MC58113 Developer Kit board
- · Pro-Motion software
- Software Development Kit (SDK) with C-Motion
- Complete manual set
- Complete cable and prototyping connector set





# **TUNE & OPTIMIZE** Pro-Motion® GUI

Pro-Motion is a sophisticated, easy-to-use Windows-based exerciser program for use with PMD motion control ICs, modules, and cards.

# **FEATURES**

- Motion oscilloscope graphically displays processor parameters in real-time
- Autotuning
- Ability to save and load settings
- Axis wizard
- Distance and time units conversion

- Motor-specific parameter setup
- Axis shuttle performs programmable motion between two positions
- Communications monitor echoes all commands sent by Pro-Motion to the board
- Advanced Bode analysis for frequency machine response

**BUILD THE APP** C-Motion®

> C-Motion is a complete, easy-to-use, motion programming language that includes a source library containing all the code required for communicating with PMD motion ICs, boards, and modules.

### **C-MOTION FEATURES INCLUDE:**

- Extensive library of commands for virtually all motion design needs
- Develop embeddable C/C++ applications
- Complete, functional examples
- Supports PC/104, serial, CAN, Ethernet, and SPI communications

code for executing a profile and traci-

race buffer wrap mode to a one time trace aceMode(hAxis1, PMDTraceOneTime);

At the processor variables that we want to capture

tTraceVariable (hAxis1, PMDTraceVariable1, PMDAxis1) etTraceVariable (hAxis1, PMDTraceVariable2, PMDAxis1, SetTraceVariable (hAxis1, PMDTraceVariable3, PMDAxis1,

// set the trace to begin when we issue the next update command SetTraceStart(hAxis1, PMDTraceConditionNextUpdate)

// set the trace to stop when the MotionComplete event occurs

SetTraceStop(hAxis1, PMDTraceConditionEventStatus, PMDEventMotionCompleteBit, PMDTraceStateHigh); SetProfileMode(hAxis1, PMDTrapezoidalProfile);

set the profile parameters

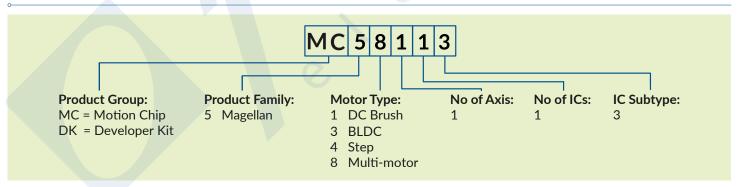
Position (hAxis1, 200000); (elocity(hAxis1, 0x200000); celeration(hAxis1, 0x1000); eleration(hAxis1, 0x1000);

# PMD PRODUCT FAMILY OVERVIEW

	# Axes	Motor Types	Format	Voltage	Communication	Features
JUNO® VELOCITY & TORQUE CONTROL ICS	1	<ul><li>Brushless DC</li><li>DC Brush</li><li>Step Motor</li></ul>	<ul><li>64-pin TQFP</li><li>56-pin VQFN</li></ul>	3.3 V	<ul><li>RS232/485</li><li>CANbus</li><li>SPI</li></ul>	<ul><li> Velocity control</li><li> Current control</li><li> Field oriented control</li></ul>
MAGELLAN® MOTION CONTROL ICS  PROFESSIONAL REPORT OF THE PROFESSIONAL	1,2,3,4	<ul><li>Brushless DC</li><li>DC Brush</li><li>Step Motor</li></ul>	<ul><li>144-pin TQFP</li><li>100-pin TQF</li></ul>	3.3 V	<ul><li>RS232/485</li><li>CANbus</li><li>SPI</li><li>Parallel</li></ul>	<ul><li>Position control</li><li>Torque/current control</li><li>Field oriented control</li><li>Profile generation</li></ul>
ATLAS® DIGITAL AMPLIFIERS	1	<ul><li>Brushless DC</li><li>DC Brush</li><li>Step Motor</li></ul>	20-pin solderable module	12-56 V	SPI     Pulse and direction	Torque/current control Field oriented control MOSFET amplifier
ION®/CME N-SERIES DIGITAL DRIVES	1	<ul><li>Brushless DC</li><li>DC Brush</li><li>Step Motor</li></ul>	Fully enclosed PCB-mounted module	12-56 V	<ul><li>Ethernet</li><li>RS232/485</li><li>CAN FD</li><li>SPI</li></ul>	<ul> <li>Position control</li> <li>Torque/current control</li> <li>Field oriented control</li> <li>Profile generation</li> <li>MOSFET amplifier</li> <li>Downloadable user code</li> </ul>
ION® 500 & 3000 DIGITAL DRIVES	1	<ul><li>Brushless DC</li><li>DC Brush</li><li>Step Motor</li></ul>	Fully enclosed cable-connected module	12-56 V 20-195 V	• Ethernet • RS232/485 • CANbus	<ul> <li>Position control</li> <li>Torque/current control</li> <li>Field oriented control</li> <li>Profile generation</li> <li>MOSFET amplifier</li> <li>Downloadable user code</li> </ul>
PRODIGY® MOTION BOARDS	1,2,3,4	<ul><li>Brushless DC</li><li>DC Brush</li><li>Step Motor</li></ul>	<ul><li>Machine Controller</li><li>PC/104</li><li>Standalone</li></ul>	• 5 V: PC/104 and Standalone • 12-56 V: Machine Controller	<ul><li>Ethernet</li><li>RS232/485</li><li>CANbus</li><li>PC/104 bus</li></ul>	<ul> <li>Position control</li> <li>Torque/current control</li> <li>Field oriented control</li> <li>Profile generation</li> <li>Downloadable user code</li> </ul>

**C-Motion**® is the common motion language for all Performance Motion Devices products.

# INFORMATION ORDERING



To place an order email purchaseorders@pmdcorp.com. For questions email support@pmdcorp.com



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Performance Motion Devices (PMD) is a worldwide leader in motion control ICs, boards and modules. Dedicated to providing cost-effective, high performance motion systems to OEM customers, PMD utilizes extensive in-house expertise to minimize time-to-market and maximize customer satisfaction.

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